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# 12. Wilberforce Pendulum

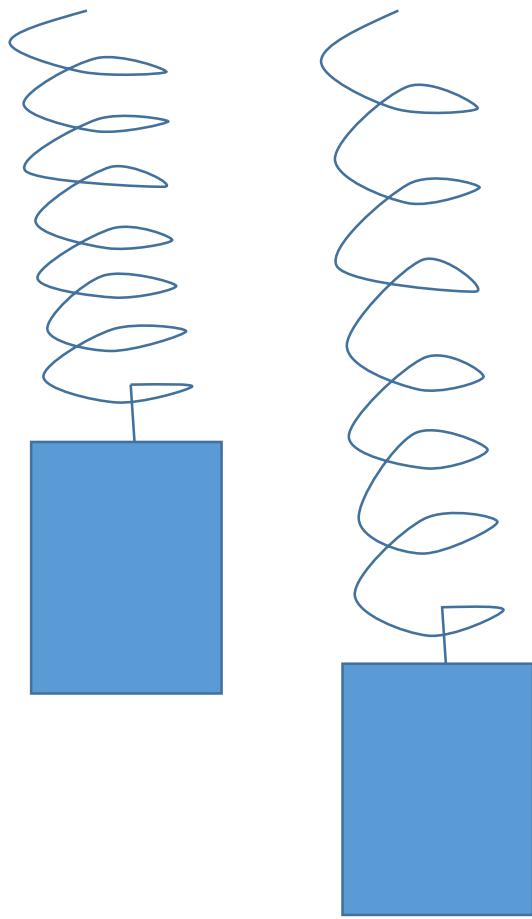
Sergej Faletič

University of Ljubljana, Faculty of Mathematics and  
Physics  
Slovenia

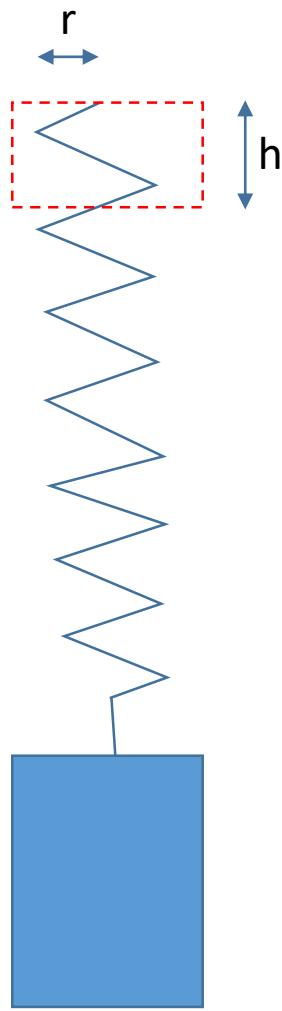
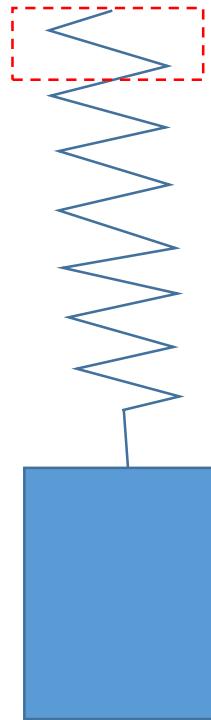
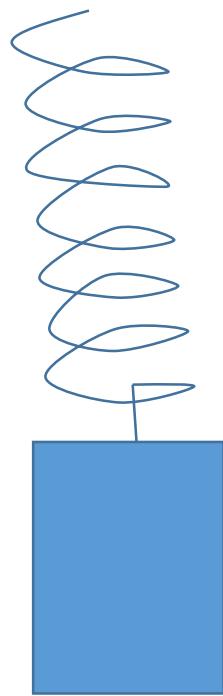
# The phenomenon

- <https://www.youtube.com/watch?v=S42ILTInfZc>

# Qualitative explanation

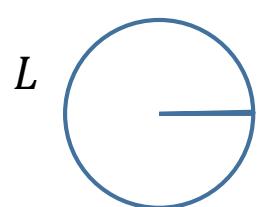


# Qualitative explanation

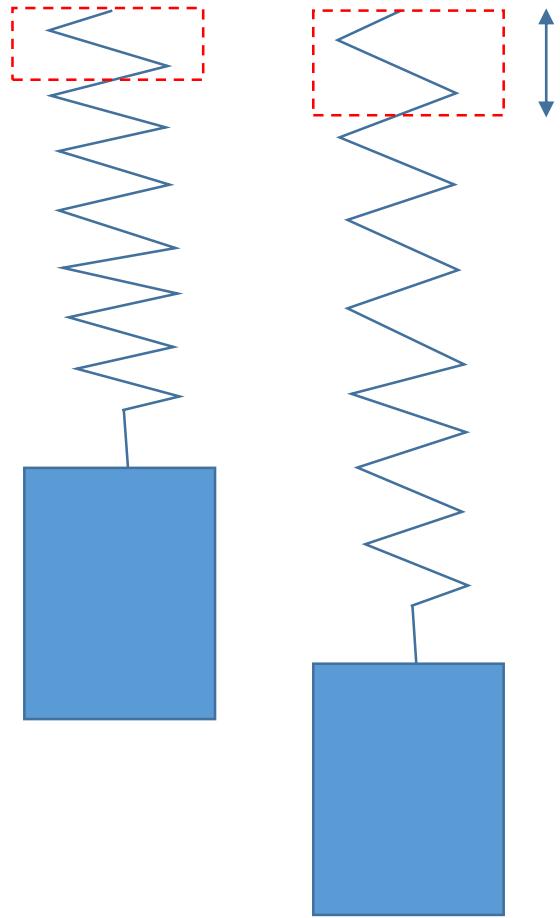
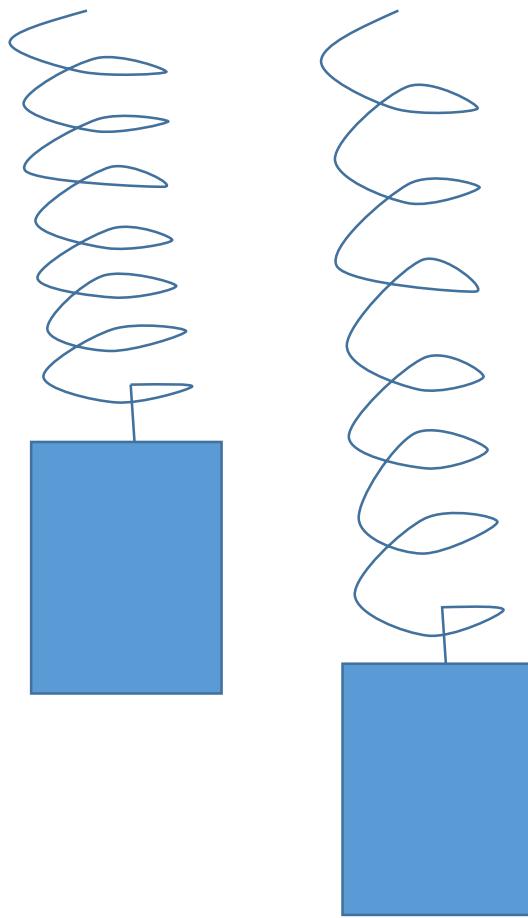


Length:  
 $L = \sqrt{h^2 + (2\pi r)^2}$

radius might change,  
but let us ignore this  
for now  
 $r = r(h)$

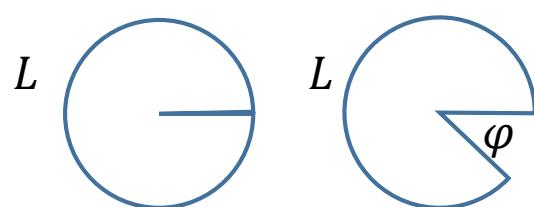


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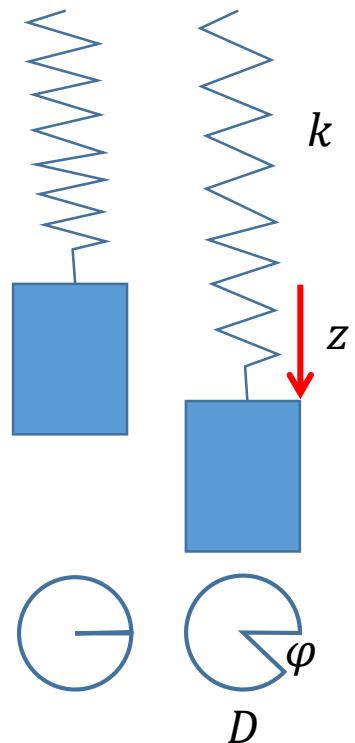
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# Calculation

$$m \frac{d^2 z}{dt^2} = -kz$$

$$I \frac{d^2 \varphi}{dt^2} = -D\varphi$$



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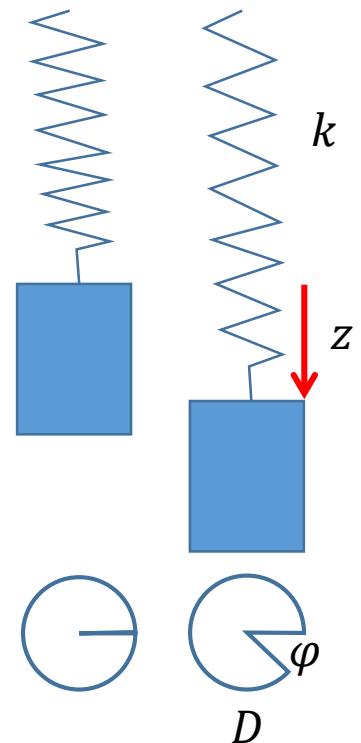
$$I \frac{d^2 \varphi}{dt^2} = -D\varphi$$

$$z(t) = A \cos(\omega_z t + \delta)$$

$$\varphi(t) = B \cos(\omega_\varphi t + \delta)$$

$$\omega_z = \sqrt{k/m}$$

$$\omega_\varphi = \sqrt{D/I}$$



# Calculation

$$m \frac{d^2 z}{dt^2} = -kz - \xi \varphi$$

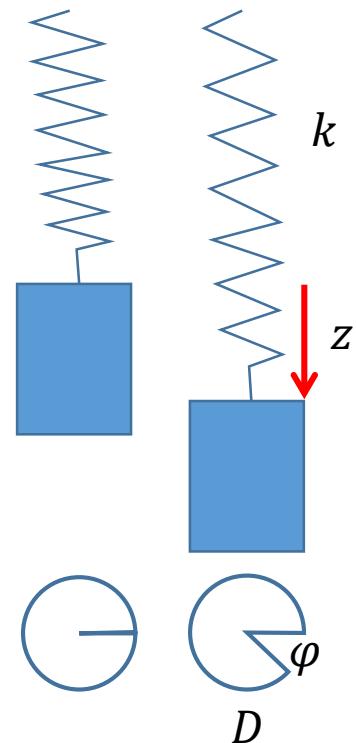
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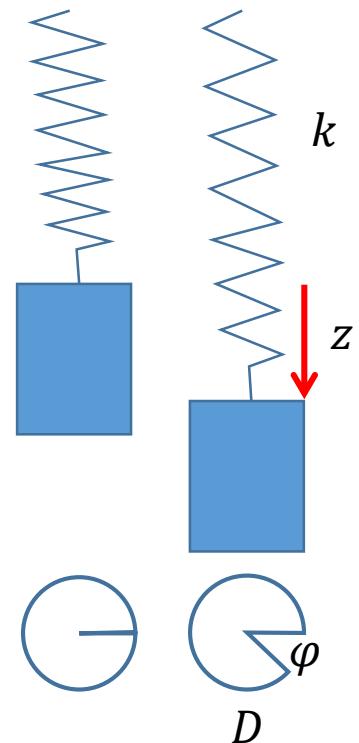
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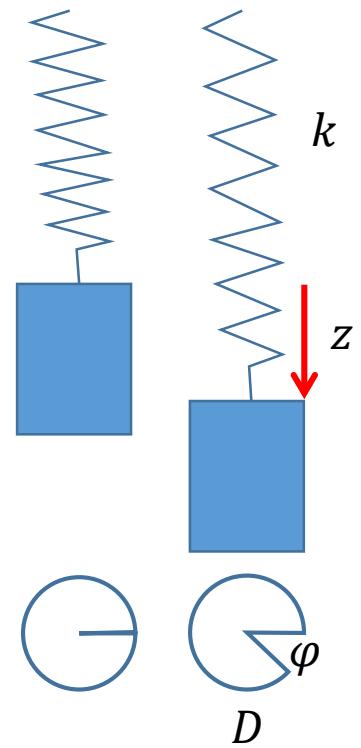
$$z(t) = A \cos(\omega t + \delta)$$

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$$\omega_{\pm}^2 = \frac{1}{2} \left[ \omega_z^2 + \omega_\varphi^2 \pm \sqrt{(\omega_z^2 - \omega_\varphi^2)^2 + \frac{4\xi^2}{mI}} \right]$$



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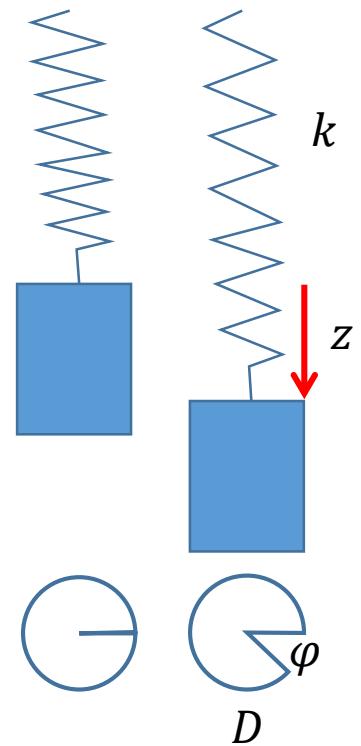
$$\varphi(t) = B \cos(\omega t + \delta)$$

$$\omega_\varphi = \sqrt{D/I}$$

$$\omega_{\pm}^2 = \frac{1}{2} \left[ \omega_z^2 + \omega_\varphi^2 \pm \sqrt{(\omega_z^2 - \omega_\varphi^2)^2 + \frac{4\xi}{mI}} \right]$$

$$z(t) = A_+ \cos(\omega_+ t + \delta_+) + A_- \cos(\omega_- t + \delta_-),$$

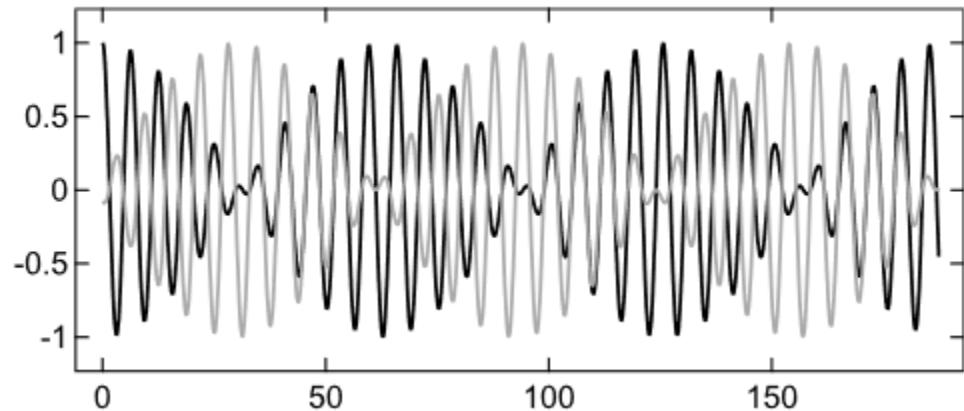
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# Calculation results

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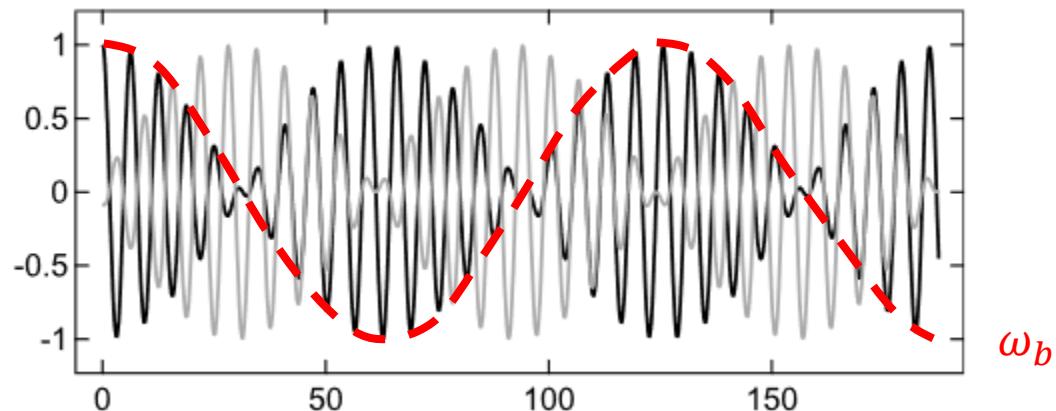
$$\varphi(t) = B_+ \cos(\omega_+ t + \delta_+) + B_- \cos(\omega_- t + \delta_-).$$



# Calculation results

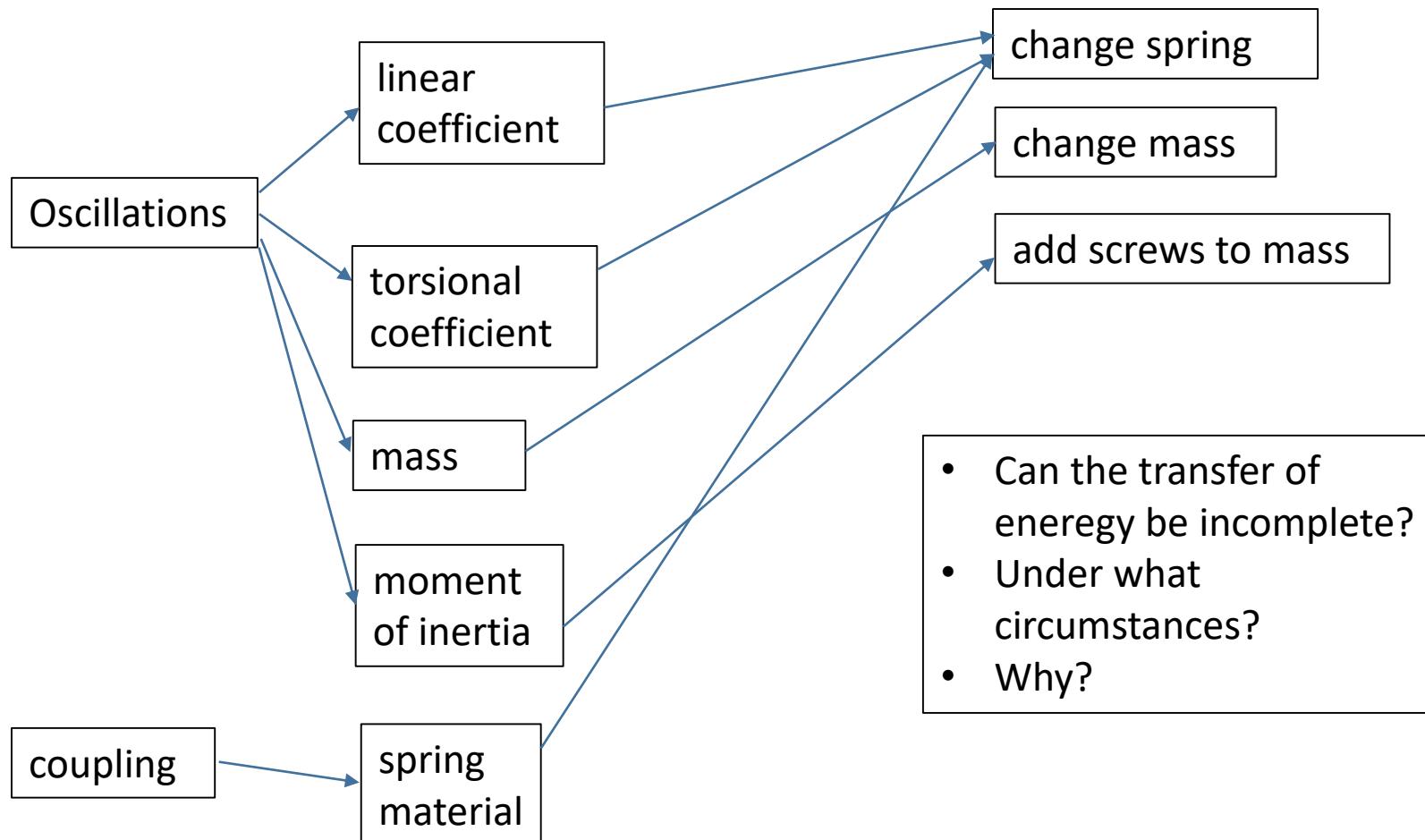
$$z(t) = A_+ \cos(\omega_+ t + \delta_+) + A_- \cos(\omega_- t + \delta_-),$$

$$\varphi(t) = B_+ \cos(\omega_+ t + \delta_+) + B_- \cos(\omega_- t + \delta_-).$$



$$\omega_{\pm}^2 = \frac{1}{2} \left[ \omega_z^2 + \omega_{\varphi}^2 \pm \sqrt{(\omega_z^2 - \omega_{\varphi}^2)^2 + \frac{4\xi}{mI}} \right]$$

# Possible parameters to investigate



- Additions

## B. The spiral spring

The spring of the Wilberforce pendulum must be adjusted to the mass and the rotational inertia of the pendulum bob. Assuming an ideal spring, i.e., a negligible mass and rotational inertia (*vide infra*), the angular frequencies of the translational and rotational oscillations are, respectively,  $\omega_z = \sqrt{k/m}$  and  $\omega_\varphi = \sqrt{\kappa/I}$ . The spring and torsion constants are related to material properties via<sup>23</sup>

$$k = \frac{1}{8} \cdot \frac{G}{D^3} \cdot \frac{d^4}{n}, \quad (9)$$

$$\kappa = \frac{1}{3670} \cdot \frac{E}{D} \cdot \frac{d^4}{n}, \quad (10)$$

( $G$ : shear modulus,  $E$ : Young modulus,  $d$ : wire diameter,  $D$ : average coil diameter,  $n$ : number of windings), which yields

$$D = \sqrt{\frac{1835}{4} \cdot \frac{\kappa}{k} \cdot \frac{G}{E}}, \quad (11)$$